



VISUAL
PHYSICS

SHORT NOTES

C H A P T E R

Reflection

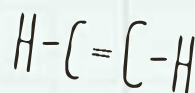
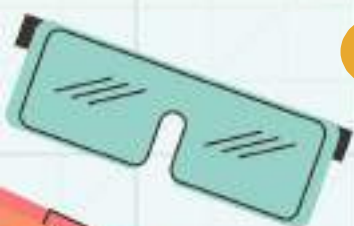
Available at:



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REFLECTION

↪ bouncing back

Normal : perpendicular to the surface

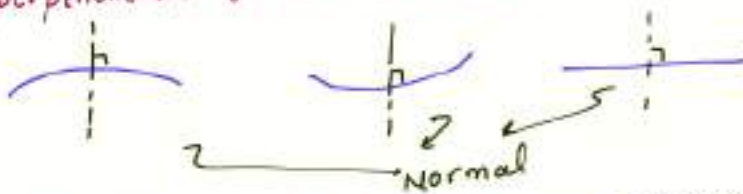
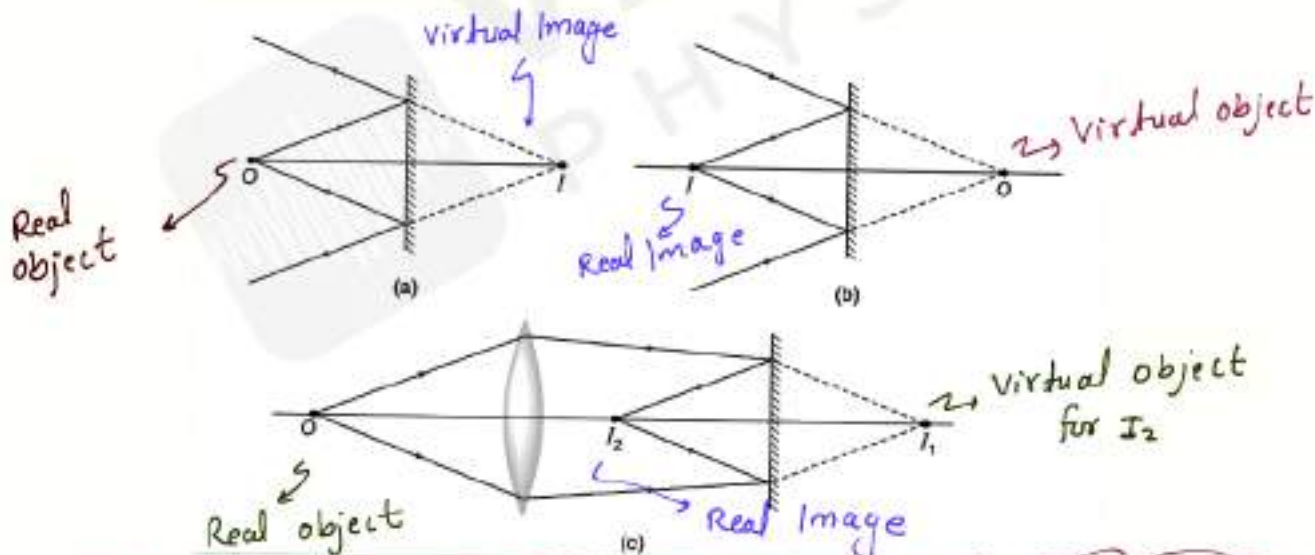


Image is formed → Reflection
or → Refraction

minimum two rays are required by image formation

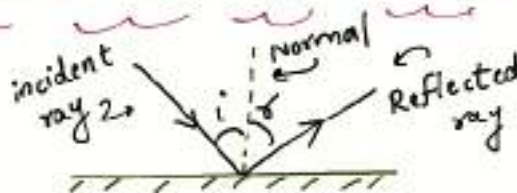
Real object, virtual object, real image, virtual image

- * The point where the rays meet (or appear to meet) before refraction or reflection is called object
- * The point where the rays meet (or appear to meet) after reflection or refraction is called image
- if rays actually meet → Real object, Real image
- if rays appear to meet → virtual object, virtual image



{ Virtual Images cannot be taken on screen, but can be seen by eye }

Law of Reflection:



- $\angle i = \angle r$
- Incident ray, reflected ray and normal lie on the same plane.

* Important points in Reflection laws:

(i) $\angle i = \angle r$ applied for any type of surface

(ii) If incident ray, reflected ray & normal are represented in form of vector, then these three should be coplanar



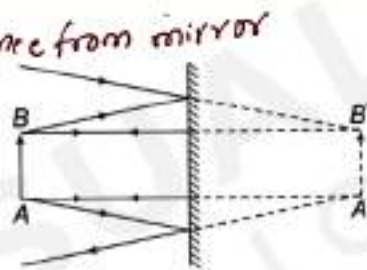
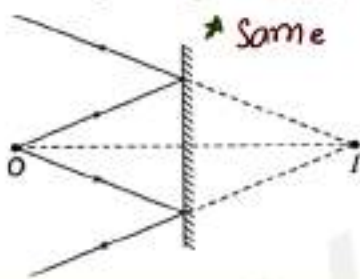
{ Reflection from a plane surface (plane mirror) }

→ Real object : Virtual Image

* Erect Image

* Same Size

* Same distance from mirror



Sign convention:

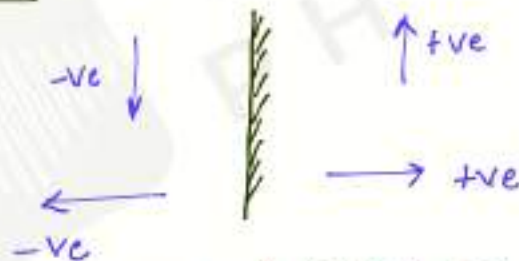


Image distance = v & object distance = u

* v & u are perpendicular distance from the mirror

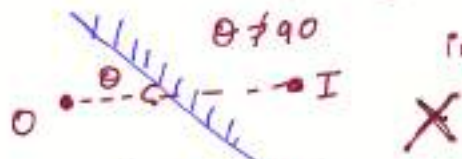
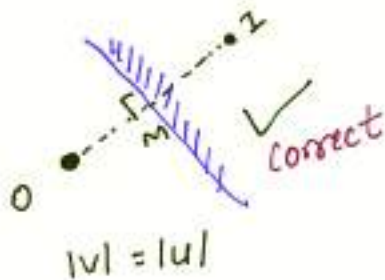
$$v = -u$$

→ according to sign convention

$$\text{or } |v| = |u|$$

$\theta \neq 90^\circ$

incorrect



distance should be measured perpendicular

★ To draw Ray diagram use two rays coming out of each ends of the object

eye must lie in this region to see the image

point object

two rays

O → Real
I → Virtual

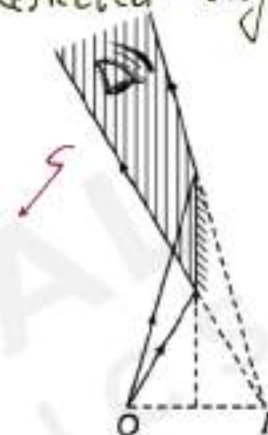
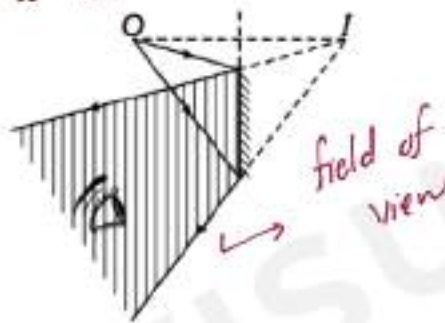
object

two rays from both ends

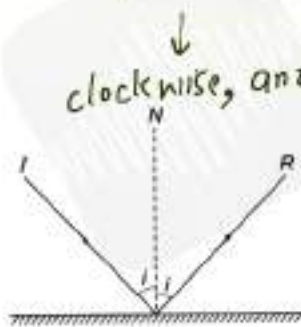
(ii)

ab → Real
a'b' → Virtual

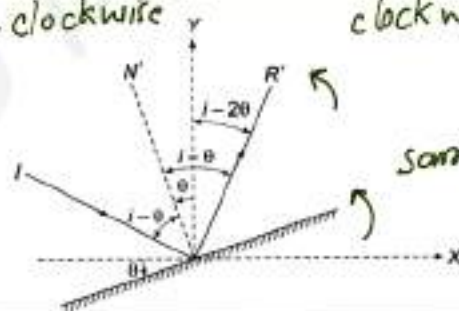
★ {Field of view of an object} Region between the extreme Reflected rays
↳ it depends on the location of object in front of the mirror



★ If mirror rotates by θ , reflected ray rotates 2θ in same direction



clockwise, anti-clockwise

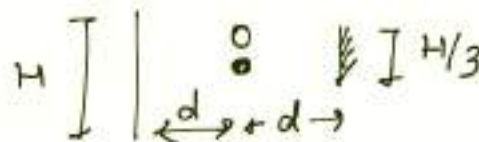


clockwise, anti-clockwise

same direction

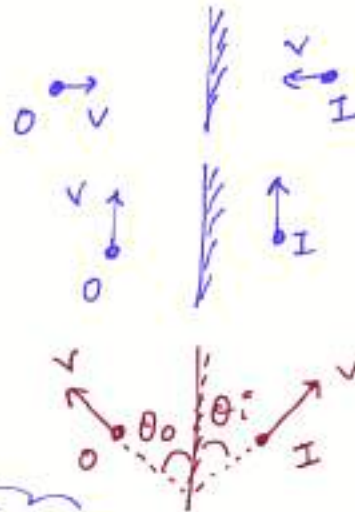
★ $\left\{ \begin{array}{l} H \\ \hookrightarrow \text{Height of object} \end{array} \Rightarrow \frac{H}{2} \hookrightarrow \text{length of mirror to see full image} \right.$

★ $H = \text{Height of wall}$
 $\frac{H}{3} = \text{length of mirror}$ if observe is exactly at mid way between wall & mirror



* object & image velocity

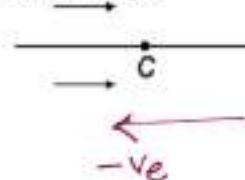
- Image speed = object speed
- $\theta_i = \theta_o$ with mirror
- velocities component along mirror are equal
- velocities component perpendicular to mirror are equal & opposite



{ Reflection from spherical surface }

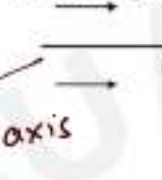
$R \rightarrow$ Radius of curvature
 $= CP$

Incident light



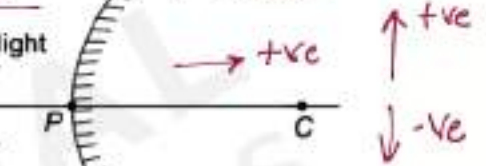
(a) Concave mirror

Incident light

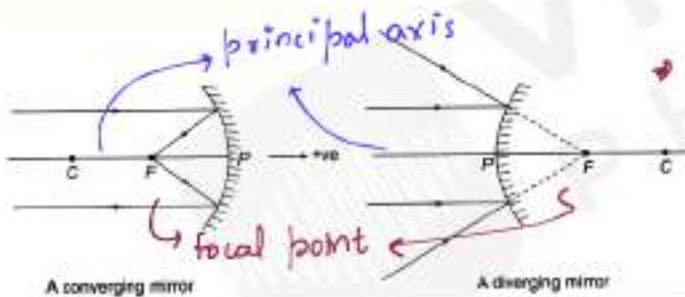


$C \rightarrow$ Centre of curvature

$P \rightarrow$ Pole



(b) Convex mirror



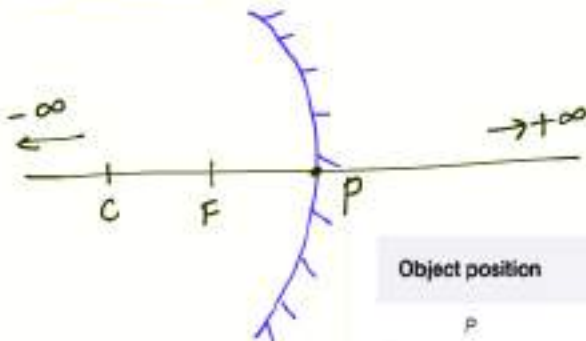
A converging mirror

A diverging mirror

$$PF = f = R/2$$

* paraxial rays: Rays close to principal axis and nearly parallel to it.

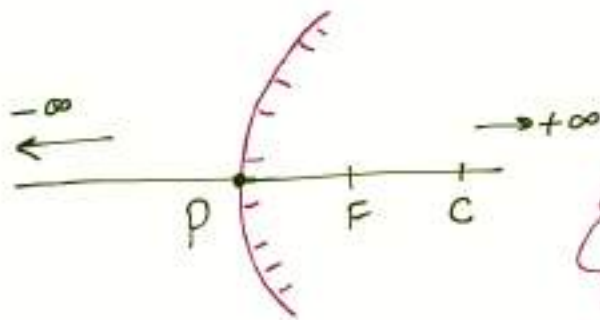
Concave mirror:



Object position	Image position	Image nature	Object speed and image speed
P	P	-	-
F	$\pm \infty$	-	-
C	C	Real, inverted and same size	$v_i = v_o$
Between P and F	Between F and $+\infty$	Virtual, erect and magnified	$v_i > v_o$
Between F and C	Between $-\infty$ and C	Real, inverted and magnified	$v_i > v_o$
Between C and $-\infty$	Between C and F	Real, inverted and diminished	$v_o > v_i$

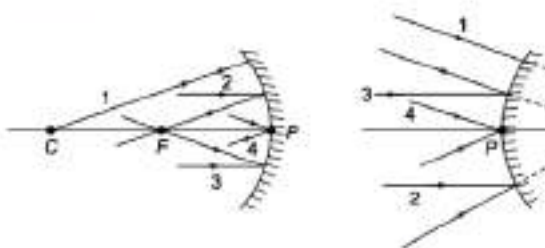
Convex mirror:

Image formed by convex mirror is always virtual, erect & diminished no matter where the object is



Convex mirror field of view > Concave mirror field of view

Ray diagrams:



- Ray 1: A ray through C
- Ray 2: A ray parallel to principal axis
- Ray 3: Ray passing through focal length
- Ray 4: A ray striking pole P.

using these 4 rays one can draw any ray diagrams

Image formation in Convex Mirror

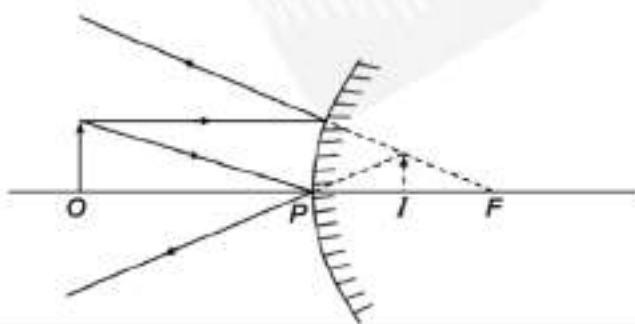
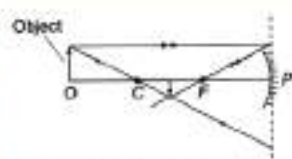
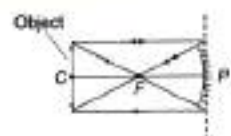


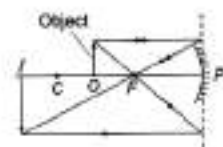
Image formation in Concave mirror



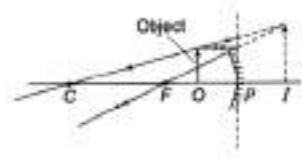
(a) Object beyond C
Image between C and F, real, inverted, diminished



(b) Object at C
Image at C, real, inverted, same size

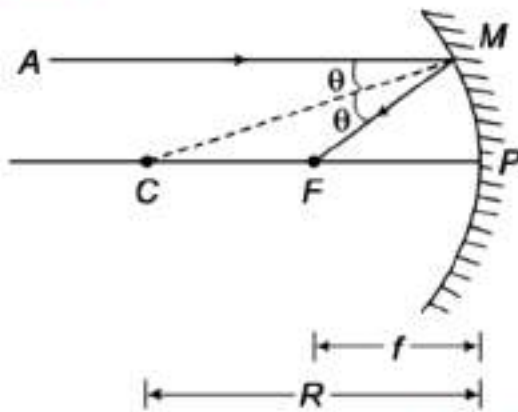


(c) Object between C and F
Image beyond C, real, inverted, magnified



(d) Object between F and P
Image behind mirror, virtual, upright, magnified

Relation between f and R :



$\angle i = \angle r$ (law of reflection)

$\angle AMC = \angle CMF = \theta$

$\angle AMC = \angle MCF$ (alternate angles)

$\angle CMF = \angle MCF$

$\Rightarrow \triangle FCM$ is isosceles [$FC = FM$]

The rays are paraxial and so M is very close to P .

$$\Rightarrow FM \approx FP$$

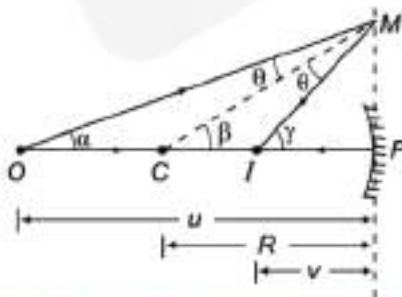
$$\therefore FC = FP$$

$$FP = \frac{1}{2} CP$$

$$\Rightarrow \left\{ f = \frac{R}{2} \right\}$$

Mirror formula

$$\alpha \approx \tan \alpha = \frac{MP}{OP}, \quad \beta = \frac{MP}{CP}, \quad \gamma = \frac{MP}{IP}$$



$\triangle CMO$, $\beta = \alpha + \theta$ (exterior angle)

$$\theta = \beta - \alpha \quad \text{--- (i)}$$

$\triangle CMI$, $\gamma = \beta + \theta$

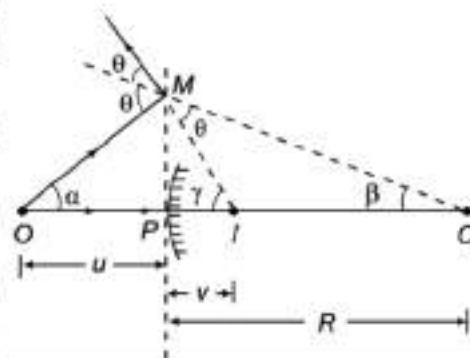
$$\theta = \gamma - \beta \quad \text{--- (ii)}$$

from (i) & (ii)

$$2\beta = \gamma + \alpha \quad \text{--- (iii)}$$

putting values of β, γ & α

$$\frac{2}{CP} = \frac{1}{IP} + \frac{1}{OP}$$



$\triangle CMO$,

$$\theta = \alpha + \beta \quad \text{--- (i) [exterior angle]}$$

$\triangle CMI$, $\gamma = \theta + \beta$

$$\theta = \gamma - \beta \quad \text{--- (ii)}$$

from (i) & (ii)

$$2\beta = \gamma - \alpha$$

$$\frac{2}{CP} = \frac{1}{IP} - \frac{1}{OP}$$

Now, $CP = -R$, $IP = -v$ & $OP = -u$ | $CP = +R$, $IP = +v$, $OP = -u$

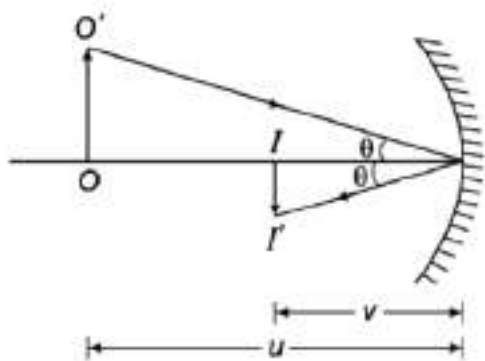
$$\frac{2}{R} = \frac{1}{v} + \frac{1}{u}$$

$$\left\{ \frac{1}{v} + \frac{1}{u} = \frac{1}{f} \right\}$$

$$\frac{2}{R} = \frac{1}{v} + \frac{1}{u}$$

$$\left\{ \frac{1}{f} = \frac{1}{v} + \frac{1}{u} \right\}$$

Magnification



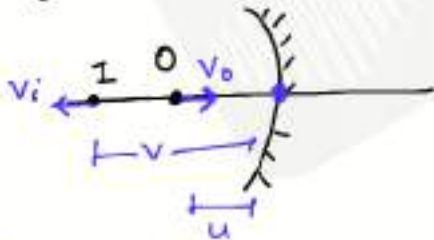
$m = \frac{\text{Height of image}}{\text{Height of object}} = \frac{I'I'}{O'O}$
 as $I'I'$ is negative $= -\frac{IP}{OP}$ { similar triangles }

$\therefore IP = -v$ & $OP = -u$

$$m = -\frac{v}{u}$$

Image velocity

Along principal axis



$$\frac{1}{v} + \frac{1}{u} = \frac{1}{f}$$

$$-v^{-2} \frac{dv}{dt} - u^{-2} \frac{du}{dt} = 0$$

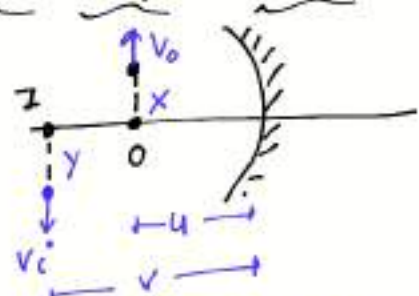
$\approx$ object speed

image speed $\frac{dv}{dt} = -\left(\frac{v^2}{u^2}\right) \frac{du}{dt}$

$$m^2 = \frac{v^2}{u^2}$$

$$\Rightarrow V_i = -m^2 V_o$$

Along perpendicular to principal axis



as u & $v = \text{constant}$

$$m = \frac{I}{O} = \frac{y}{x}$$

$$\frac{dy}{dt} = m \frac{dx}{dt}$$

$$V_i = m V_o$$